

Surveillance Event Detection

NHK STRL

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Surveillance Event Detection (SED) task

Automatic extraction of specific action sequences



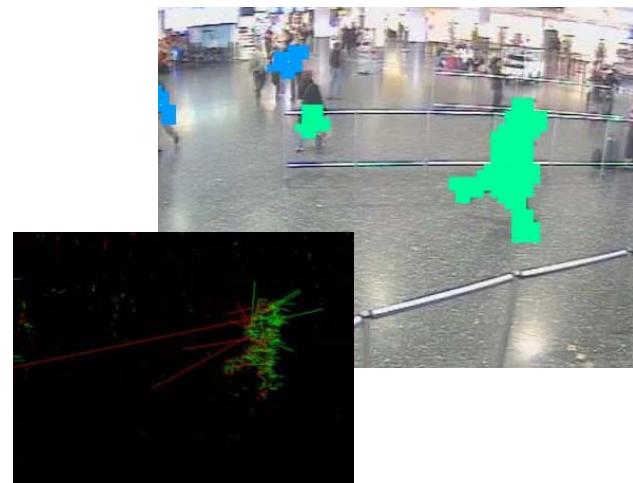
NHK STRL has been participating in the SED task for 4 years

Proposed method

2008

▶ Optical flow-based

- Objects were detected on the basis of direction and magnitude of optical flow
- Events were detected by using random forest classifier



2009

▶ Human region detection-based

- Human regions were detected by calculating HOG features
- Events were detected on the basis of features from a single trajectory



Proposed method

2010

► Bag-of-trajectories-based

- Extracted several key-point trajectories
- Recognized events on the basis of histogram of optical flows

→ Bag: entire image



2011

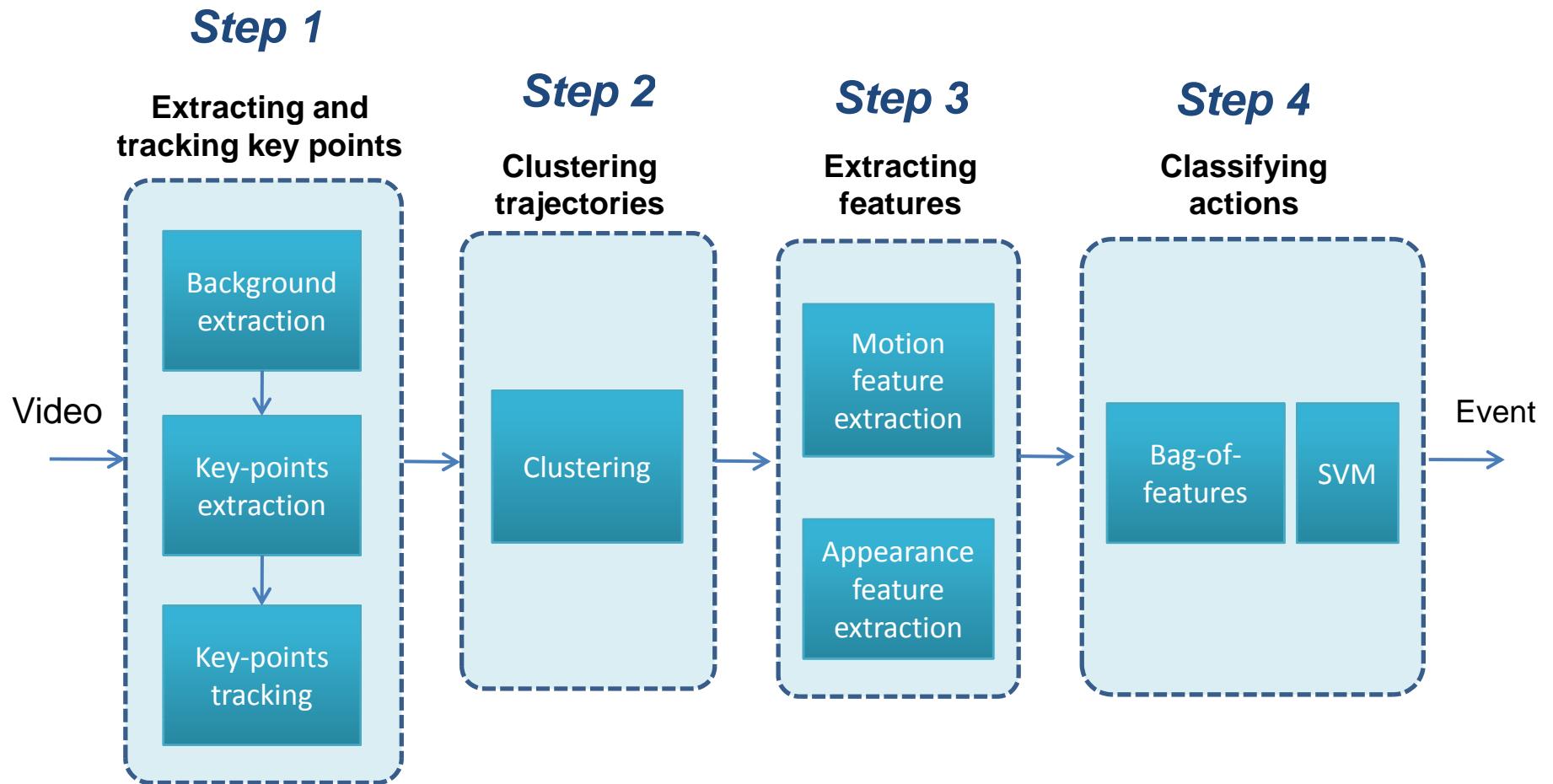
► Enhanced bag-of-trajectories

- Clusters the human regions
- Considers the magnitude of optical flow in addition to its direction

→ Bag: a cluster region

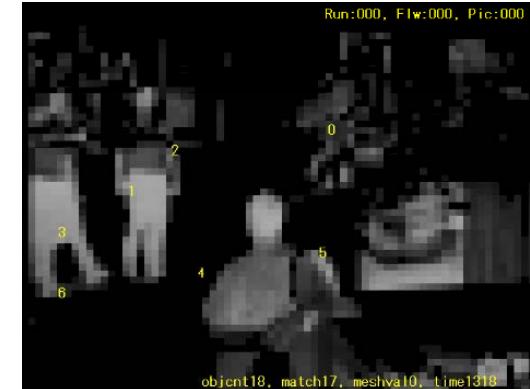
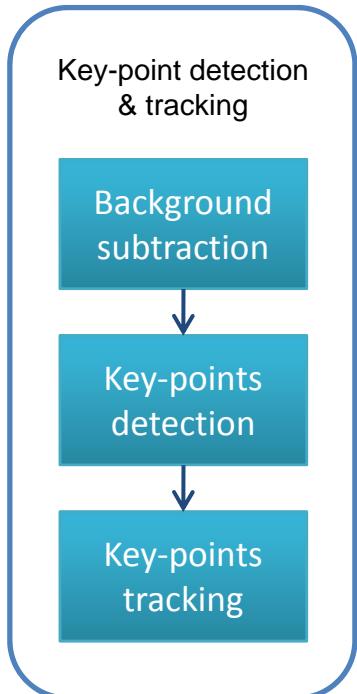


Processing flow



- ▶ Events are recognized for each person by clustering human regions
- ▶ The feature is invariant of the duration of trajectories

Step 1: Key-points detection & tracking



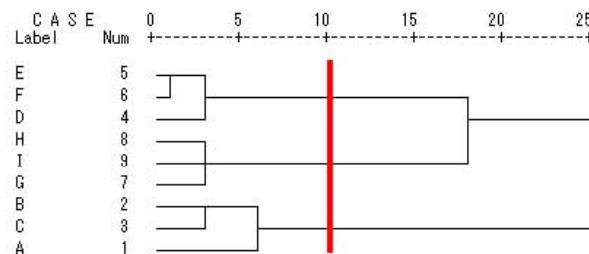
Background subtraction



Key-point trajectories

Step 2: Clustering human regions

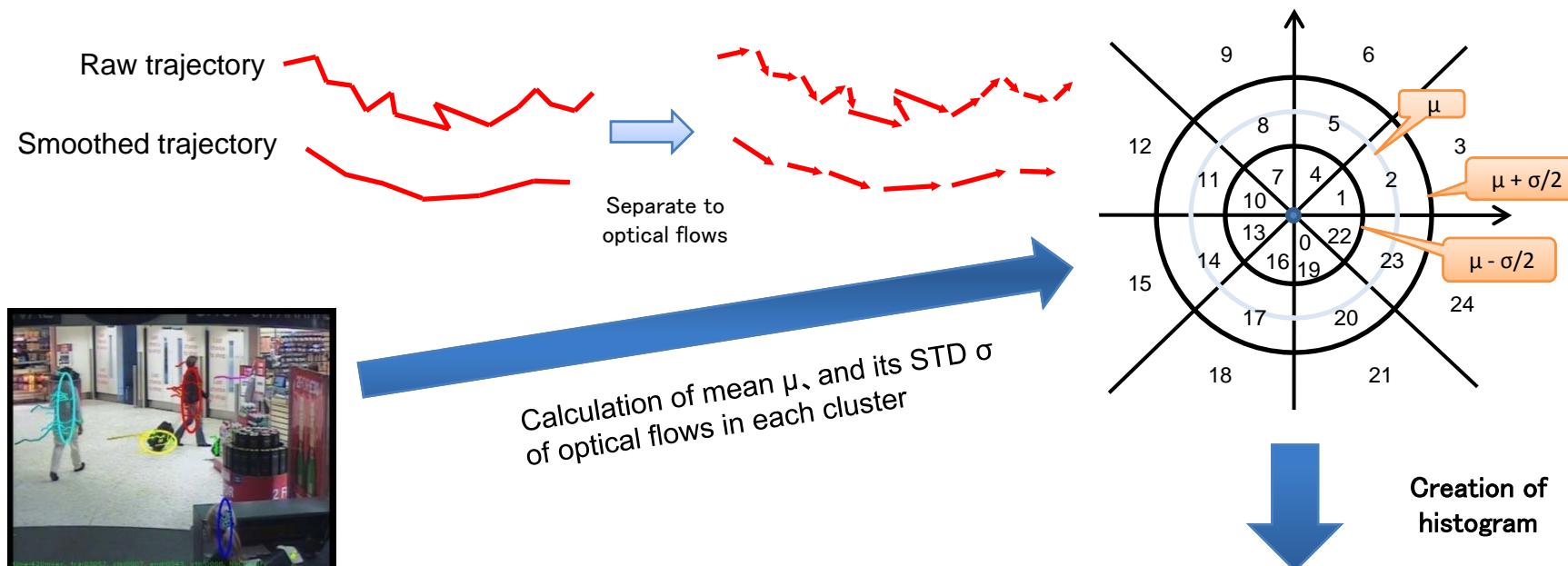
- ▶ Clustering object regions on the basis of distance between each trajectory



- ▶ Each cluster region is used as a bag in the bag-of-features approach
- ▶ The threshold was decided on the basis of original annotated bounding boxes

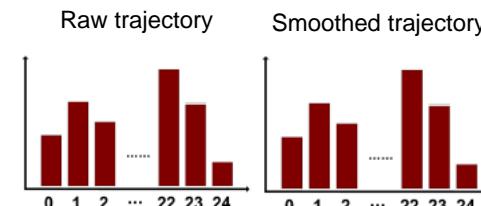
Step 3: “Motion” feature

▶ Creation of trajectory histogram



Merits of trajectory histogram

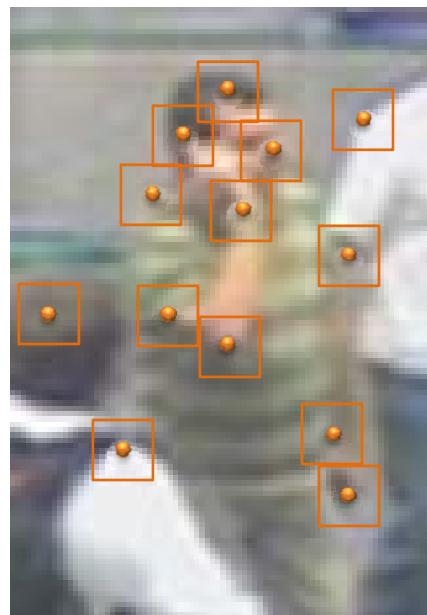
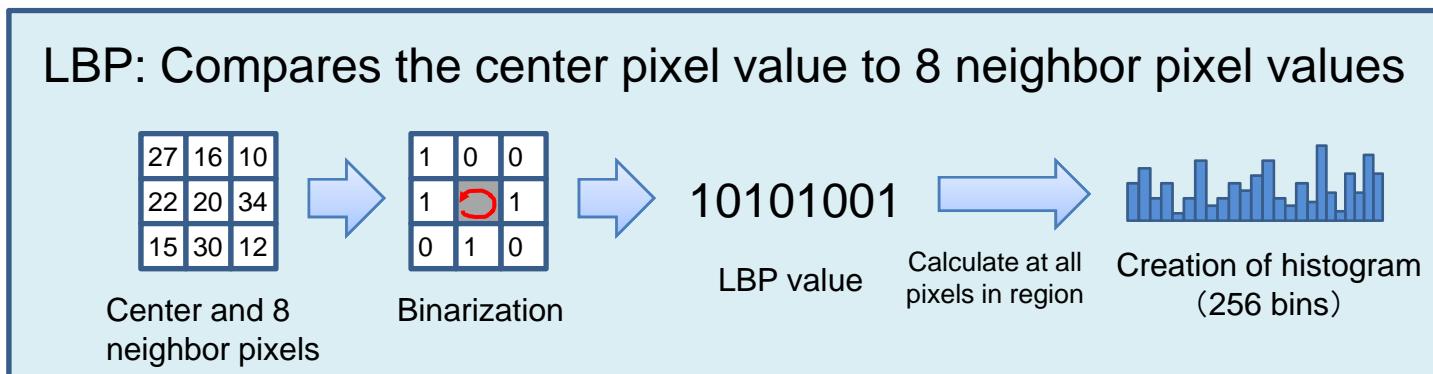
- ▶ Fixed feature dimension → BoF approach is possible
- ▶ Invariant of individual motion speed



Trajectory histogram
50 bins (25 bins \times 2)

Step 3: “Appearance” feature

▶ Creation of local binary pattern (LBP) histogram



Calculates LBP values at key-point centered 16×16 pixels



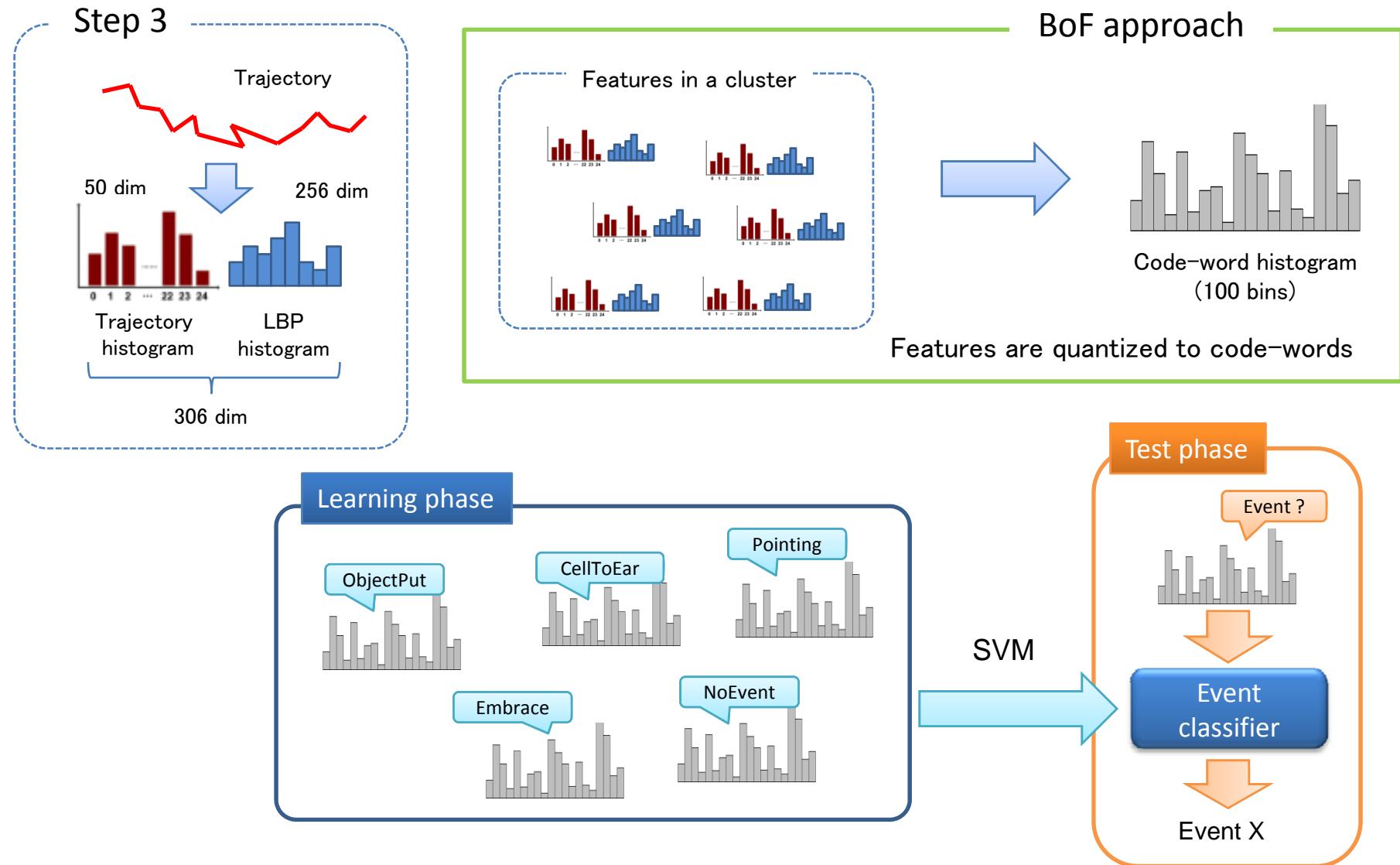
Create an LBP histogram and use it as a feature

Merits of using LBP

- ▶ Robust recognition by considering “appearance” feature
- ▶ Faster than other local image features, such as SIFT or SURF

Step 4: Event classification

► Bag-of-features approach + SVM



Results

▶ Evaluation results by NIST

Event	#Reference	#System	#CorDet	#FA	#Miss	DCR
CellToEar	194	165	3	162	191	1.0377
Embrace	175	835	31	804	144	1.0865
ObjectPut	621	562	10	552	611	1.1649
Pointing	1063	1278	41	1237	1022	1.3671

- ▶ The results for “CellToEar” were relatively stable: the action was regular and there were few motion elements.
- ▶ The proposed method was not robust for events that had significant direction variations

Experiment

► Comparison with human tracking-based method

Event: ObjectPut

Method	N_{ref}	N_{Sys}	N_{CorDet}	N_{FA}	N_{Miss}	R_{FA}	P_{Miss}	DCR
Human tracking-based	621	488	19	469	602	30.760	0.969	1.123
Proposed	621	1061	39	537	582	35.219	0.937	1.113

- The consideration of several key-point trajectories improves performance of human motion recognition
- Human detection and tracking is not robust with crowded video sequences



Conclusion

- ▶ The proposed method can robustly recognize human motion by using trajectory histograms that are invariant to individual motion speed.
- ▶ The extracted trajectories are clustered depending on their positions.
- ▶ Appearance features are considered in addition to motion features.

Future work

- ▶ Apply our proposed methods to other applications, such as auto tagging of motion metadata or user interfaces for TV viewing.

Thank you.