

Semantic Indexing

System overview: 1) Features based on pre-trained and fine-tuned deep convolutional neural networks (DCNN); 2) Dimensionality reduction using Kernel Subclass Discriminant Analysis (KSDA); 3) Cascade of classifiers using local and DCNN-based descriptors; 4) Multi-task learning (MTL) using the logistic-lasso algorithm; 5) Two-layer stacking architecture

System A: Cascade of four stages; 11 visual descriptors, one LSVM per descriptor (3xORB, 3xSIFT, 3xSURF, 2xDCNN-based)

System B: Cascade as in A, with features reduced to a much lower dimension using KSDA

System C: One MTL model for each of the reduced descriptors in B; per-concept late fusion of the MTL models' scores

System D: Late fusion of 7 DCNN-based descriptors, using 5 LR models per descriptor; resulting in 35 LR models per concept

	MXinfAP
System A	0.239
System B	0.258
System C	0.219
System D	0.232

ITI-CERTH-Runs	MXinfAP
Run1	0.263
Run2	0.26
Run3	0.25
Run4	0.252

ITI-CERTH-Run1: "Combination". Combination of A through D

ITI-CERTH-Run2: "MTL-LogLasso". Combination of C and D

ITI-CERTH-Run3: "Cascade KSDA". Combination of B and D

ITI-CERTH-Run4: "Cascade". Combination of A and D

- **Runs 3 and 4:** Similar accuracy; the cascades offered $\approx 37\%$ less classifier evaluations compared to the late fusion alternative
- **Run 2:** Slight improvement due to Multi-task learning
- **Run 1:** Marginal improvement over previous runs

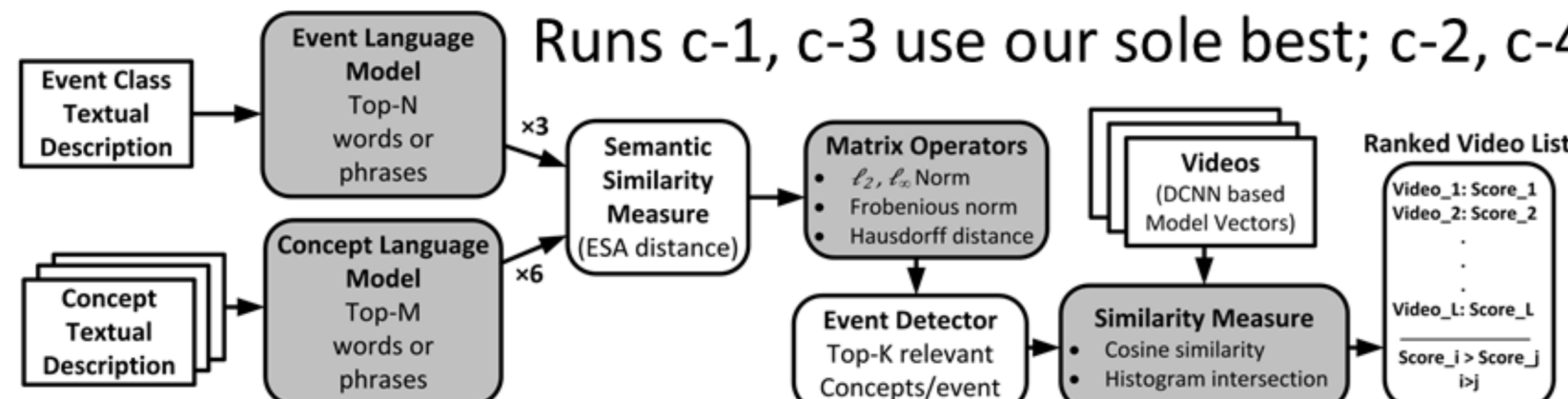
Multimedia Event Detection

In 010Ex and 100Ex:

- **KSDA+LSVM** (c-1KDALSVM used visual, motion, fc7+fc8 DCNN descriptors); achieved better results; 2nd best among all contestants on 100Ex
- **RDKSVM** (c-2RDKSVM used fc8, c-3RDKSVM used fc7+fc8); exploits near-miss videos; performance limited by descriptors

In 000Ex:

3 ELMs*6 CLMs*4 mat. op. = 72 detectors;
 Runs c-1, c-3 use our sole best; c-2, c-4 use top-10 average.



Fusion of multiple detectors leads to performance increase.

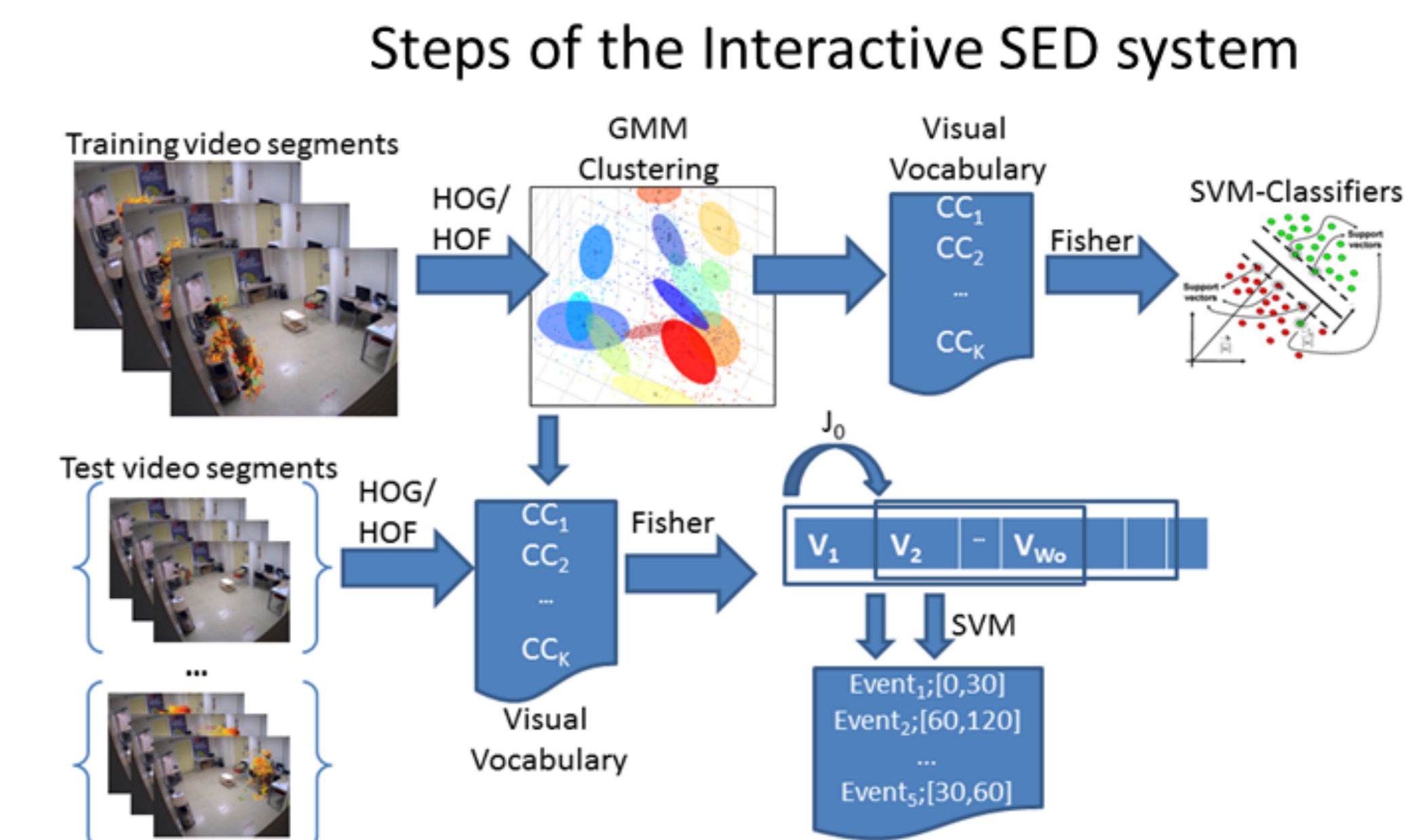
	010Ex	100Ex
Run ID	mInfAP@200	mInfAP@200
p-1Fusion	0.211	0.3649
c-1KDALSVM	0.2493	0.4111
c-2RDKSVM	0.1588	0.2894
c-3RDKSVM	0.2026	0.2367

	000Ex
Run ID	mInfAP@200
p-1Fusion	0.0617
c-1oneCosine	0.0478
c-2avgCosine	0.0473
c-3oneHist	0.0474
c-4avgHist	0.0592

Surveillance Event Detection

Activity detection system stages:

- **Offline Stage:** Extraction of Dense Trajectories + HOG/HOF descriptors; Fisher encoding; LSVM model training
- **Online Stage:** a 50-frame sliding window along with pre-trained models for localizing the desired events inside test videos



5 Events of interest: Embrace, PeopleMeet, Pointing, PersonRuns, and PeopleSplitUp

Event	Embrace	PeopleMeet	Pointing	PersonRuns	PeopleSplitUp
Metric					
ADCR	0.9855	0.9990	1.0054	0.9834	0.9868
MDCR	0.9855	0.9984	1.006	0.9823	0.9868

Instance Search

- Participation with VERGE interactive video search engine
- VERGE retrieval and presentation modules
 - High Level Visual Concept Retrieval (Semantic Indexing)
 - Object-based Visual Search Module
 - Fast Hessian detector + SIFT descriptor for local feature extraction
 - BoW model: 2-layer Visual Vocabulary (100K) construction using Repeated Bisecting K-Means
 - Inverted Index implementation using Apache Lucene search engine library
 - Capability of querying the system either with whole frames or any cropped part of them
 - Support of Multiple Queries
 - Similarity Score: Borda Count based on tf-idf weights and ranking positions in the retrieved list
 - Best performance with fusion of baseline BoW + Saliency-based BoW models

VERGE GUI (<http://mklab-services.iti.gr/trec2015/>)

Modules	Run IDs		
	1	2	3
Baseline BoW model	✓		✓
Saliency detection		✓	✓
MAP	0.053	0.046	0.064

Evaluation of INS results