# IRISA @ TRECVID2017

# Beyond Crossmodal and Multimodal Models

Task: Video Hyperlinking

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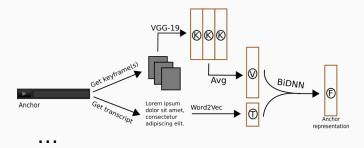
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# Introduction

## A crossmodal system

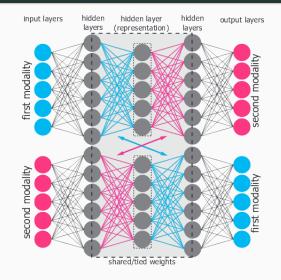
In 2016, IRISA used a crossmodal system[1]:

- Segmentation step
  - $\rightarrow$  Get segments from whole videos
- Segments/anchors embedding step:



- Comparing and ranking step
  - $\rightarrow$  For each anchor, compare and rank each segment

# The **BiDNN**



### This system had the best score on P@5

 $\rightarrow$  Go further with this approach?

# Segmentation

In 2016, we had around 300,000 segments

- $\rightarrow$  Limited number of segments
- $\rightarrow$  Problems with the overlap

Create more segments!

Some constraints:

- $\rightarrow$  The segment should not cut the speech
- $\rightarrow$  They must last between 10 and 120 seconds

With a constraint programming framework:

- Keep all the segments that last between 50 and 60 seconds without cutting the speech
- When there we none, expand the duration between 10 and 120 seconds

1.1 million new segments  $\rightarrow$  1.4 million segments in total (around 4 times more)

Representations

Our model greatly depends on the quality of the representation of each modality

 $\rightarrow$  Can we improve them?

**Development set**: each triplet (anchor, target, matching) submitted last year

We extracted/recovered:

- For each anchor, its transcript and one or more keyframes
- For each target, its transcript and one keyframe

Embedding of the keyframes using different pre-trained CNNs (VGG-19[7], ResNet[2], ResNext[9] and Inception[8])

When multiples keyframes, there was an additional step of *keyframe representation fusion*:

- Single: Using a single keyframe and discarding the rest
- <u>Avg</u>: The embedding is the average of all of the keyframes embeddings
- <u>Max</u>: Each feature of the embedding is the maximum of all keyframes corresponding feature

	Single		Average		Max	
Models	P@5	P@10	P@5	P@10	P@5	P@10
VGG19	41.60	41.27	43.40	41.60	42.60	41.03
Inception	40.40	41.83	41.00	41.39	42.60	41.73
ResNext-101	41.00	39.37	41.40	40.10	41.80	39.90
ResNet-200	43.80	41.57	47.20	44.37	47.60	44.87
ResNet-152	44.40	41.37	45.60	41.67	45.20	40.40

 $\rightarrow$  We chose to use a  $\mathit{ResNet-200}$  network and a  $\mathit{Max}$  keyframe representation fusion method

Same experiments with transcripts:

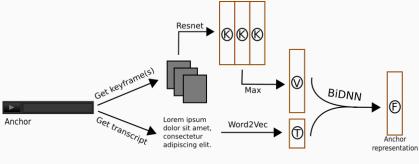
Models	P@5	MAP	
Average Word2Vec[5]	44.2	45.3	
Doc2Vec[4]	38.4	39.4	
Skip-Thought[3]	40.2	41.6	

 $\rightarrow$  We chose to keep  $\mathit{Word2Vec}.$ 

# Runs description

# BiDNNFull - Crossmodal Bidirectional Joint Learning

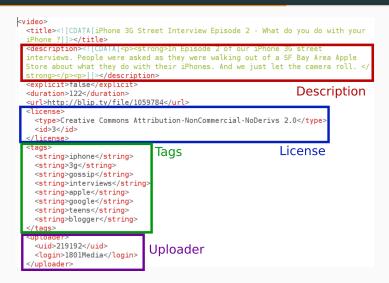
A bidirectional deep neural network (BiDNN) was trained with ResNet as a visual descriptor and a Word2Vec as a textual descriptor:



. . .

 $\rightarrow$  BiDNNFull is our baseline for testing other improvements to the system.

# BiDNNFilter - BiDNN with metadata filter



We chose to keep the *list of tags* as a filter to compare anchors and targets that **share at least one tag in common**.

## BiDNNFilter - BiDNN with metadata filter

However:

- 77% of videos have tags
- They have a mean number of tags of 4.71

Too restrictive?

Use the text of the descriptions:

- Selection of only verbs, nouns and adjectives
- Lemmatization
- Exclusion of stopwords and hapaxes

 $\rightarrow$  *BiDNNFilter* is the same as *BiDNNFull* but with the addition of the **list of keywords**—tags and description—used as a filter.

Some issues about the keyframe representation fusion method:  $\rightarrow$  Basic treatment of information contained in multiple keyframes

We use the Moore-Penrose pseudo-inverse:

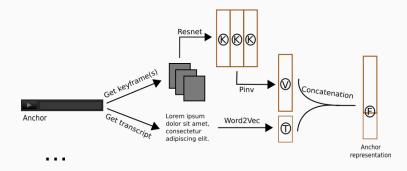
- Capures a notion of movement between multiple keyframes
- Deals with different variations found across all keyframes.
- It can improve the search quality[6].

 $\rightarrow$  BiDNNPinv is the same as BiDNNFull where the Max function is replaced by the pseudo-inverse.

# NoBiDNNPinv - Concatenation with pseudo-inverse

# Quantify the usefulness of the BiDNN in this system

We replaced the BiDNN by a L2-normalization followed by a concatenation:



 $\rightarrow$  NoBiDNNPinv's embedding pipeline is described by the picture.

# Results

Runs	MAP	MAISP	P@5	P@10	P@20
BiDNNFull	13.34	10.14	68.80	71.20	42.40
BiDNNFilter	10.81	8.43	76.00	74.40	38.00
BiDNNPinv	15.29	11.52	75.20	74.40	43.40
noBiDNNPinv	12.46	10.16	72.80	73.20	39.60

- *BiDNNFilter* obtained the best P@5 and P@10 showing the interest of **the filter to increase precision**.
- *BiDNNPinv* obtained the best MAP, MAISP and P@20 showing the **pseudo-inverse gives more precision stability**.
- The score difference between *BiDNNPinv* and *noBiDNNPinv* confirms the **relevance of the crossmodal model**.

# Conclusion

Adding a filter increases the precision

The pseudo-inverse succeeds at capturing relevant information on multiple keyframes

We can think of future interesting developments:

- Combine both the filter and the pseudo-inverse
- Incorporate the metadata within the neural network, using it as a third modality
- Use the pseudo-inverse on both anchors and targets

# Thank you for your attention!

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## Some good/bad cases

#### BiDNNFilter:

#### Good cases

- anchor\_131: good description + tags
- anchor\_132&137: good description with no tags

### Bad cases

- anchor\_124: very general tags  $\rightarrow$  not better than BiDNNFull
- anchor\_126: only three tags that do not describe the video (grit, grittv, laura\_flanders)
- anchor\_141: no tags and a very long description (709 words)

#### BiDNNPinv:

### Good cases

• anchor\_141: an anchor with a lot of keyframes?

The bad cases are hard to identify

#### Moore-Penrose pseudo-inverse

Given a set of anchor vectors represented as columns in a  $d \times n$  matrix  $X = [x_1, ..., x_n]$  where  $x_i \in R^d$ :

$$m(X) = X(X^{\mathsf{T}}X)^{-1}\mathbf{1}_n \tag{1}$$

where  $\mathbf{1}_n$  is a *n* dimensional vector with all values set to 1.