

## Kobe University and Kindai University at TRECVID 2018 AVS Task

Kimiaki Shirahama<sup>1</sup>, He Zhenying<sup>2</sup> and Kuniaki Uehara<sup>2</sup> Department of Informatics, Kindai University Graduate School of System Informatics, Kobe University

**Cascade Construction** 



**Cascade-based Retrieval** 

Topic 566: Find shots of a dog playing outdoors

Outdoor (1)

outdoor (4)

Dogs (1)

dog (3)

high

sore

low

score

Final score =

Outdoor (1)

outdoor (4)

Indoor (1)  $\times 0.5$ 

Dogs (1)

dog (3)

Indoor (1)

score =

Dogs (1)

dog (3)

high

sore

Result

filter out

half with

low

score

1. Normalize detection scores

power normalization

min-maxnormalizatio

filter out

half with

low score

rank

 $(\alpha = 0.15)$ 

2. Filter out

3. Rank

Outdoor (1)

outdoor (4)

Dogs (1)

dog (3)

Indoor (1)

score =

Outdoor (1)

outdoor (4)

Top 1000

Indoor (1) × 0.5

### Abstract

This year we addressed the following two points:

- How to fuse concept detection scores for accurate retrieval Cascade-based approach that uses a sequence of stages to gradually filter out irrelevant shots
- How to deal with a topic requiring the number of objects or their relation **Object detection** to analyze detected regions

### **Concept detection**

**345 SIN concepts:** Detection scores that are provided by ITI-CERTH team and obtained by SVM-based fine-tuning of pre-trained network

1000 ImageNet concepts: ResNet152 implementation in YOLO to detect 1000 concepts in **ImageNet** 

9418 ImageNet concepts: darknet9000 to detect 9418 concepts that are organized into a hierarchical tree

### 385 Places concepts: ResNet152 fine-

tuned for 365 scene concepts defined in Places 365, as well as max-pooling to obtain detection scores for their 20 super-concepts

**487 Sports1M concepts: C3D** to detect 487 concepts defined in Sports1M dataset.

## 1000 9418 **ImageNet**

**Negative concept:** 

indoor

### **Concept Selection**

1. Generality: Use the most general concept

e.g. Topic 566: Find shots of a dog playing outdoors

2. Specificity: Use a specific concept deduced from a phase in a topic

e.g. Topic 563: Find shots of one or more people on a moving boat in the water

boatman

a) Cascade for Topic 561: Find shots of exactly two men at a conference or meeting table talking in a room Meeting (1)

c) Separate cascades: Multiple cascades are

used for a topic including "or"

Selected concepts are organized into a cascade

where each concept is associated with one stage

a) Order of stage: As a concept is more general,

the corresponding stage is placed earlier

b) Parallel: Multiple concepts representing the

same (or very similar) meaning are placed in

Conference Room (1)

conference room (3)

table (3)

table (3)

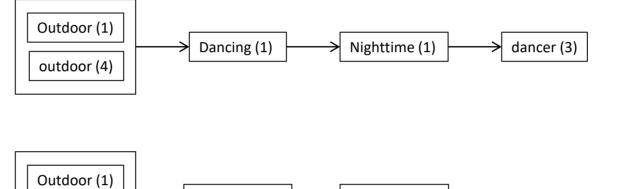
b) Cascade for Topic 566: Find shots of a dog playing outdoors

Dogs (1) Outdoor (1) dog (3) outdoor (4)

Two\_People (1) Talking (1)

parallel

c) Two separate cascades for Topic 567: Find shots of people performing or dancing outdoors at night time



Nighttime (1) performer (3)

Manually Select

# Organized into a cascade

**Object Detection** by Mask R-CNN 5

Refinement Cascade **Get Retrieval Result** 

### Refinement by Object Detection

Topics with requirement on the number of objects or their spatial relationship

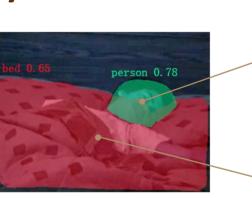
Topic 561: Find shots of exactly **two** men at a conference or meeting table talking in a room.

Topic 584: Find shots of a person lying on a bed.

Spatial relationship

### **Object detection by Mask R-CNN**





center of gravity of person By mask R-CNN we obtain label, probability and mask of object instances

center of gravity of bed

Examination of the top 10000 shots retrieved by the cascade-based approach

- **☐** Number of objects:
  - Use the number of instances with the same label in a keyframe
- ☐ Spatial relationship between objects:
  - Get center of gravity of each object instance by calculating average of all pixel coordinate in the instance mask
  - Determine the spatial relationship by comparing the center of gravity of an object to the one of another object

### **Shot filtering**



Filter out shots with not exactly two people(works well)

Filter out shots in which person's position is lower than bed's(doesn't work well)

### **Future work**

- Adopt an "embedding-based" approach to avoid cumbersome issues in the concept-based approach, like concept selection and score fusion/pooling
- Use Deep relational network to specifically predict the complex relationships between objects.

### Results

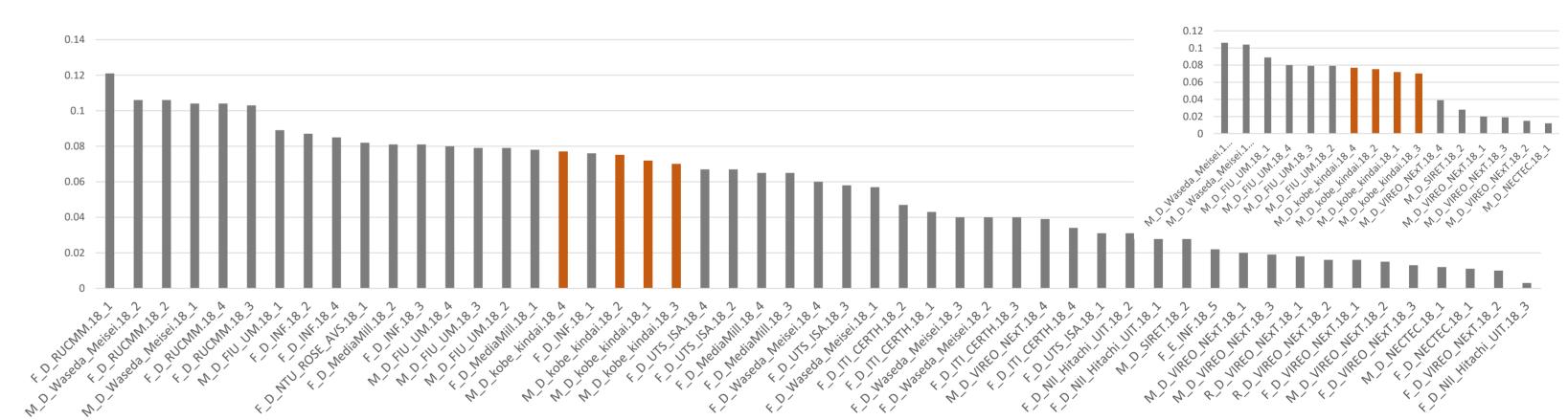
outdoor (4)

Topic

- M\_D\_kobe\_kindai.18\_1:Baseline that uses the cascade-based approach without object detection.
- M\_D\_kobe\_kindai.18\_2: Refinement of shots retrieved by M\_D\_kobe\_kindai.18\_1 with object detection
- M\_D\_kobe\_kindai.18\_3: Slightly different sets of concepts from M\_D\_kobe\_kindai.18\_1 for some topics
- M\_D\_kobe\_kindai.18\_4: Simple summation of detection scores for the selected concepts.

with stages

Concepts



- 1. M\_D\_kobe\_kindai.18 4 is ranked at the seventh place among 16 runs in the manually-assisted category. (Our team is ranked at the third place among six teams)
- 2. Adoption of the large concept vocabulary leads to good performances.



- 1. Our runs achieved the best average precisions for the six topics in the manually-assisted category.
- 2. No significant difference is observed between using the cascade-based approach and not-using it.
- Cascade-based approach reduces search time (from 5.9s to 4.0s).



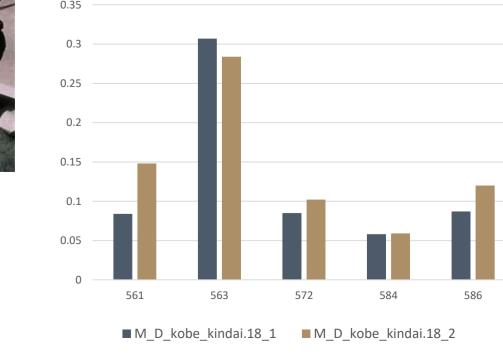




For complex relations between objects like waving

flags and pouring liquid, our current method only





standing in line outdoors. on a bed For topics requiring spatial relationship

• The person's center of gravity is higher than bed's, but the person is sitting on the bed.

For complex topic · Although we obtained masks of object instances, it's difficult to define which situation is correct.)

**Object detection** effectively refines retrieval results, especially when the number of objects is required.

considers their co-occurrence

- For topics requiring spatial relationship, object detection didn't work as good as we expected.
- For complex shot, it's difficult to define which shot is correct